Moments and Distribution of the NPV of a Project

Stefan Creemers (October 25, 2017)





Agenda

- Introduction
- Serial projects:
 - Single cash flow after a single stage
 - Single cash flow after multiple stages
 - NPV of a serial project
 - Optimal sequence of stages
- General projects
- Conclusions

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- Higher moments/distribution of project NPV are currently determined using Monte Carlo simulation
- We develop exact, closed-form expressions for the moments of project NPV & develop an accurate approximation of the NPV distribution itself

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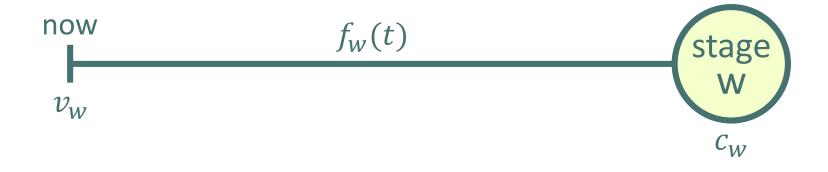
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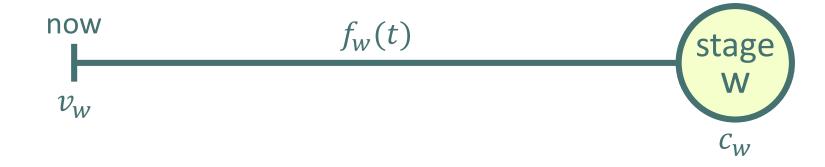
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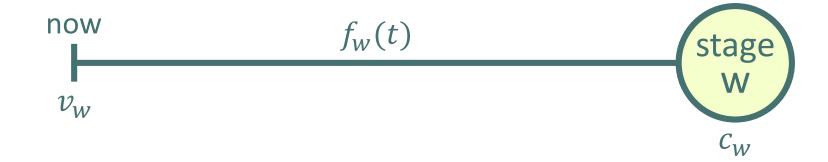


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- $f_w(t)$ = distribution of time until cash flow c_w is incurred



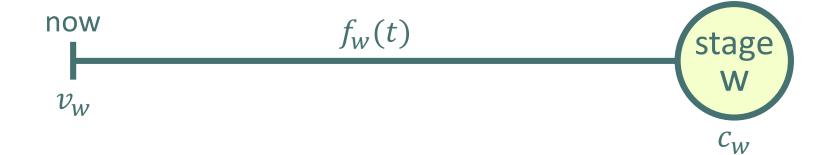
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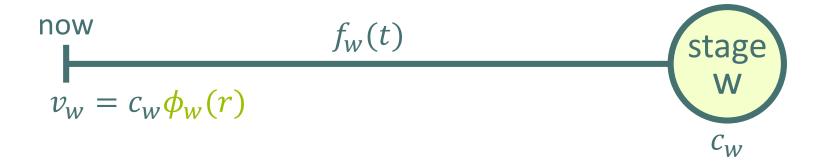
$$v_w = c_w \int_0^\infty f_w(t) e^{-rt} dt \quad v_w = c_w M_{f_w(t)}(-r)$$

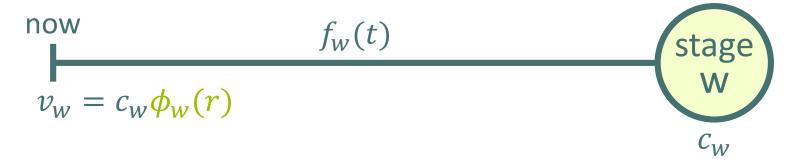
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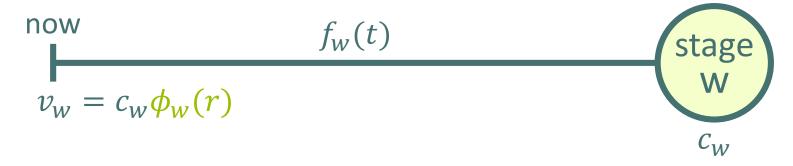
$$v_w = c_w \int_0^\infty f_w(t) e^{-rt} dt \quad v_w = c_w M_{f_w(t)}(-r) \quad v_w = c_w \phi_w(r)$$

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- $M_{f_w(t)}(-r)$ = moment generating function of $f_w(t)$ about -r
- $\phi_w(r)$ = discount factor for stage w





- Using discount factor $\phi_w(r)$, we can obtain the moments of the NPV:
 - $\mu_{w} = c_{w}\phi_{w}(r)$ $- \sigma_{w}^{2} = c_{w}^{2}(\phi_{w}(2r) - \phi_{w}^{2}(r))$ $- \gamma_{w} = c_{w}^{3}(\phi_{w}(3r) - 3\phi_{w}(2r)\phi_{w}(r) + 2\phi_{w}^{3}(r))\sigma_{w}^{-3}$ $- \theta_{w} = c_{w}^{4}(\phi_{w}(4r) - 4\phi_{w}(3r)\phi_{w}(r) + 6\phi_{w}(2r)\phi_{w}^{2}(r) - 3\phi_{w}^{4}(r))\sigma_{w}^{-4}$



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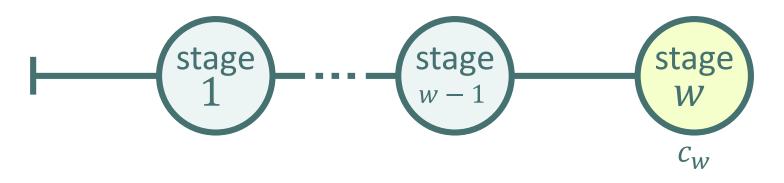
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- \theta_{w} = c_{w}^{4}(\phi_{w}(4r) - 4\phi_{w}(3r)\phi_{w}(r) + 6\phi_{w}(2r)\phi_{w}^{2}(r) - 3\phi_{w}^{4}(r)) \sigma_{w}^{-4}$$

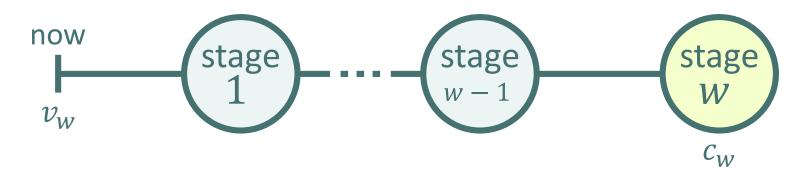
The CDF & PDF of the NPV of c_w are:

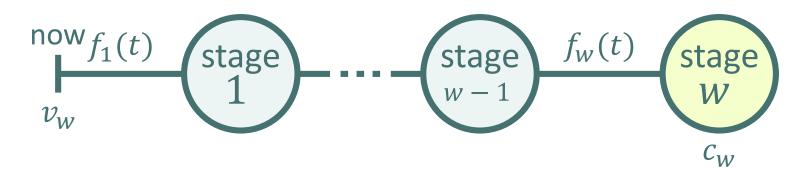
$$- G_w(v) = 1 - F_w\left(\ln\left(\frac{c_w}{v}\right)r^{-1}\right)$$
$$- g_w(v) = \frac{f_w\left(\ln\left(\frac{c_w}{v}\right)r^{-1}\right)}{|r|v}$$

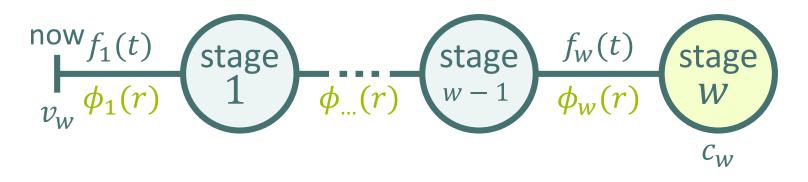
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$$\begin{array}{c|c} \mathsf{now}_{f_1(t)} & \mathsf{stage}_{1} & \mathsf{stage}_{1} & \mathsf{stage}_{w-1} & \mathsf{f}_w(t) & \mathsf{stage}_{w} \\ v_w \phi_1(r) & 1 & \phi_{\dots}(r) & w-1 & \phi_w(r) & \mathsf{stage}_{w} \\ c_w \end{array}$$

 $v_w = c_w \phi_1(r) \dots \phi_w(r)$

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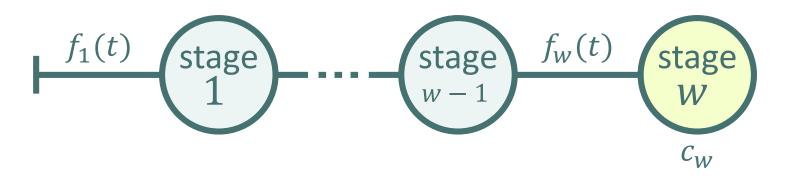
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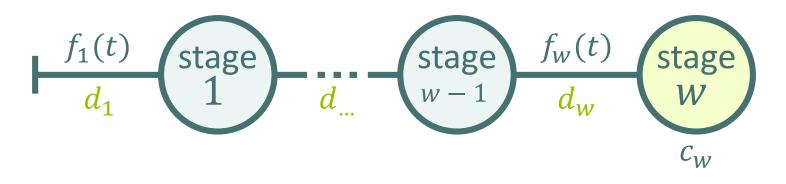
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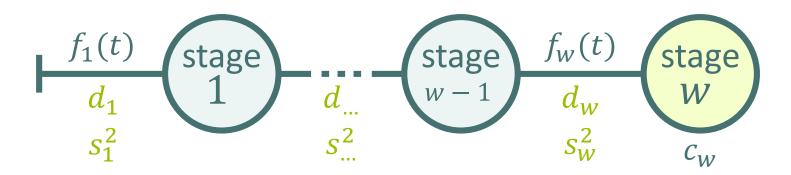
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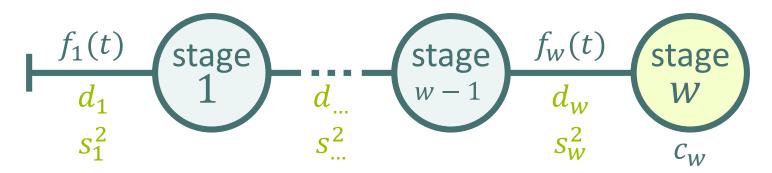
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• We can obtain the moments of the NPV of cash flow c_w : $-\mu_w = c_w \phi_{1,w}(r)$ $-\sigma_w^2 = c_w^2(\phi_{1,w}(2r) - \phi_{1,w}^2(r))$ $-\dots$





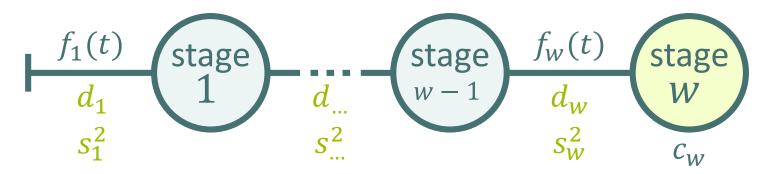




• The mean and variance of the distribution of time until cash flow *c*_w is incurred is:

$$-d_{1,w} = \sum_{i=1}^{w} d_i$$

$$- s_{1,w}^2 = \sum_{i=1}^{w} s_i^2$$

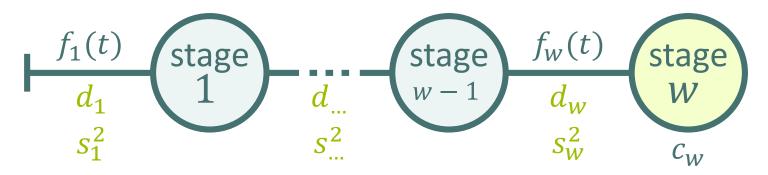


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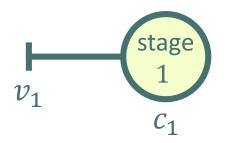
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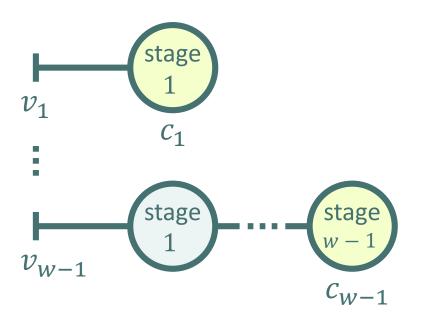
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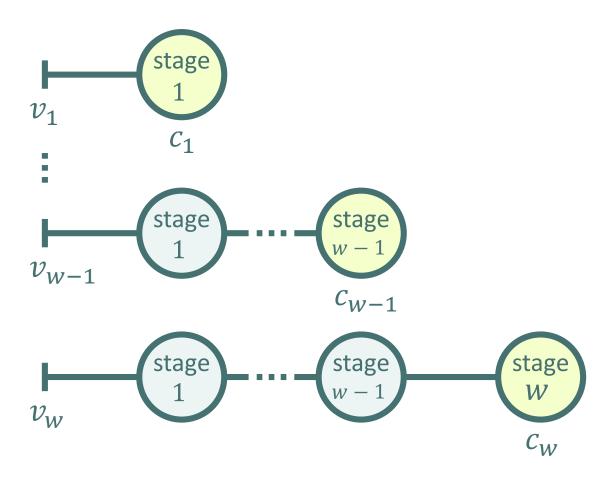
- If stage w is preceded by a sufficient number of stages, $f_{1,w}(t)$ is normally distributed with mean $d_{1,w}$ and variance $s_{1,w}^2$
- If $f_{1,w}(t)$ is normally distributed, the NPV of cash flow c_w is lognormally distributed!

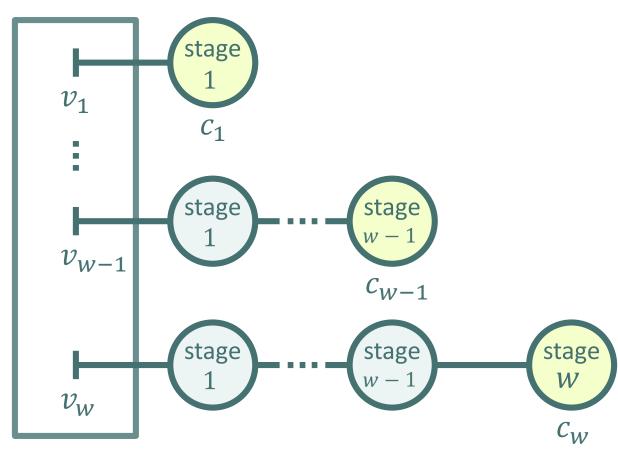
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 $v = v_1 + \ldots + v_{w-1} + v_w$

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Mean μ

 $\mu_w = c_w a_1$

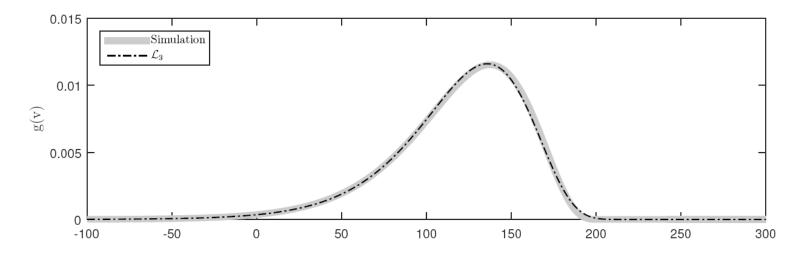
Covariance matrix Σ_c $\Sigma_c(w, w) = \sigma_w^2 = c_w^2(a_2 - a^2)$ $\Sigma_c(w, x) = c_w c_x b_1 (a_2 - a^2) = c_w^{-1} c_x b_1 \Sigma_c(w, w)$

Central coskewness matrix Γ_c $\Gamma_c(w, w, w) = \gamma_w \sigma_w^3 = c_w^3 (a_3 - 3a_2a_1 + 2a^3)$ $\Gamma_c(w, w, x) = c_w^{-1}c_xb_1\Gamma_c(w, w, w)$ $\Gamma_c(w, x, x) = c_wc_x^2 (a_3b_2 - a_2a_1 (2b^2 + b_2) + 2a^3b^2)$ $\Gamma_c(w, x, y) = c_x^{-1}c_yh_1\Gamma_c(w, x, x)$

We develop a three-parameter lognormal distribution that can be used to match the mean, variance, and skewness of the true NPV distribution

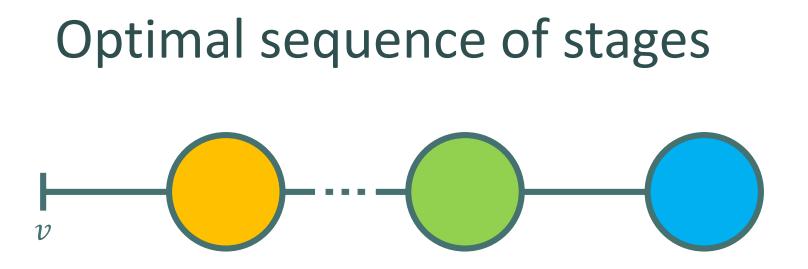
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The example below illustrates the accuracy of the threeparameter lognormal distribution (\mathcal{L}_3):

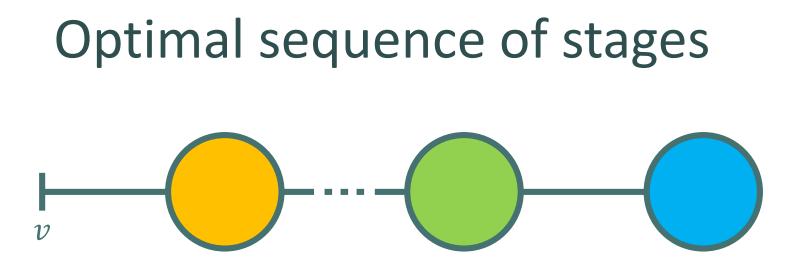


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 Moments of known sequence can be obtained using exact closed-form formulas



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- How to obtain the optimal sequence of a set of stages that are potentially precedence related?





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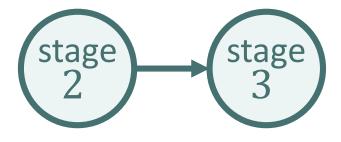
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- The LCFDP minimizes the cost of the sequential diagnosis of a number of system components
- In the absence of precedence relations, the optimal sequence can be found in polynomial time
- Efficient algorithms are available for the general case

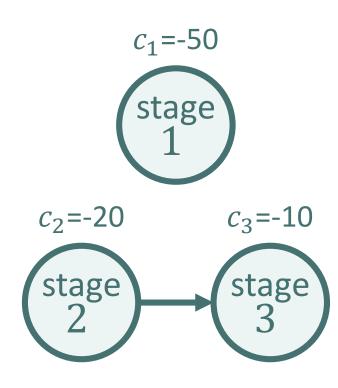
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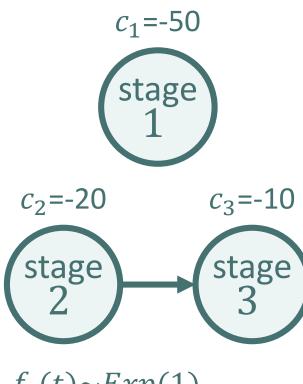
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NPV of a general project

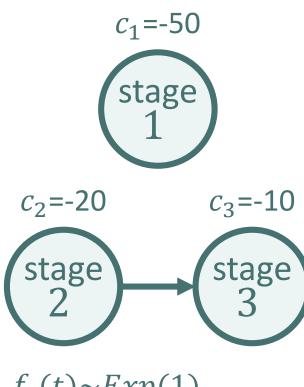




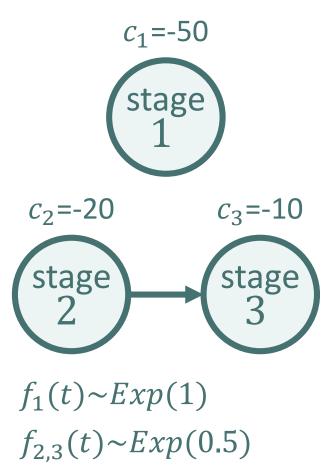




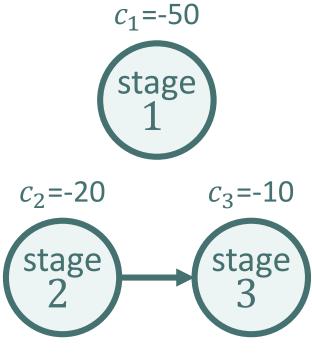
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 $f_1(t) \sim Exp(1)$ $f_{2,3}(t) \sim Exp(0.5)$ p = 200



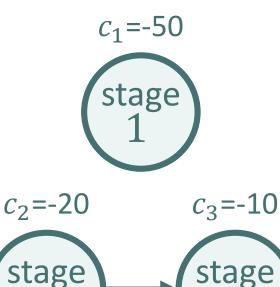
p = 200 r = 0.1



- Serial policies:

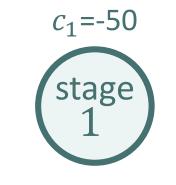
 1-2-3
 1-3-2
 - 2-1-3
 - 2-3-1
 - 3-1-2
 - 3-2-1

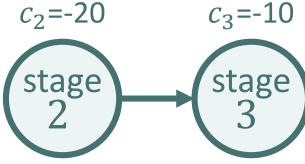
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- Early-Start (ES) policy: Start 1 & 2. Start 3 upon completion of 2.

 $f_1(t) \sim Exp(1)$ $f_{2,3}(t) \sim Exp(0.5)$ $p = 200 \quad r = 0.1$



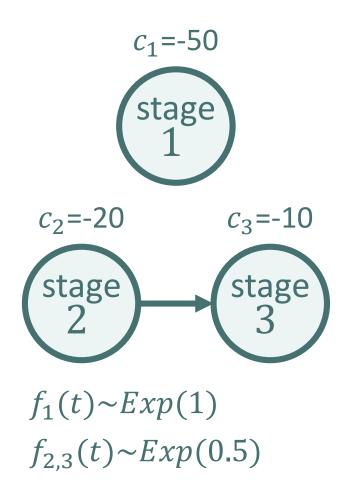


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. . .

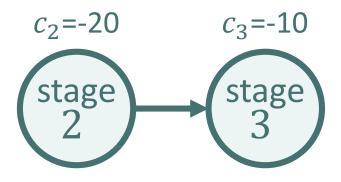
- Early-Start (ES) policy: Start 1 & 2. Start 3 upon completion of 2.
- Optimal policy: Start 2. Start 1 & 3 upon completion of 2.



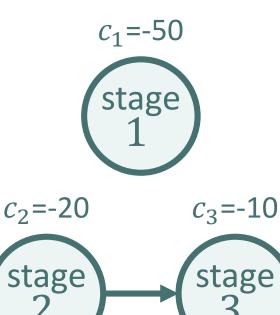
p = 200 r = 0.1



- When do we incur the payoff?
 - After stage 1?
 - After stage 2&3?



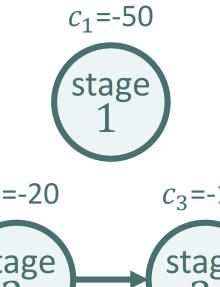
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 - After stage 2&3?
- What discount factor do we use?

 $-\phi_1(r) - \phi_{2,3}(r)$

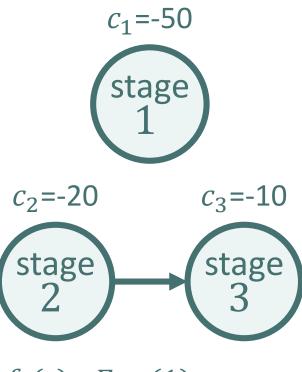
 $f_1(t) \sim Exp(1)$ $f_{2,3}(t) \sim Exp(0.5)$ p = 200 r = 0.1



 $c_2 = -20$ $c_3 = -10$ stage stage

 $f_1(t) \sim Exp(1)$ $f_{2.3}(t) \sim Exp(0.5)$ p = 200 r = 0.1

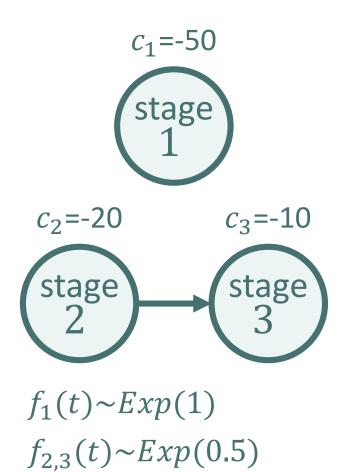
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 - $-\phi_1(r)$
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- There no longer exists a fixed sequence/the sequence is probabilistic



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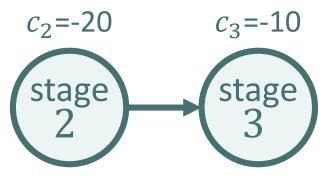
 \Rightarrow Approximations are required!



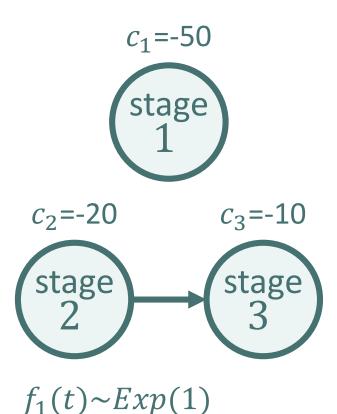
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Payoff is obtained after stage 2 & after stages 1 & 3 that are executed in parallel



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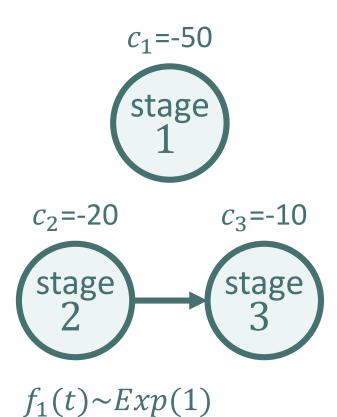


 $f_{2,3}(t) \sim Exp(0.5)$

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- Payoff is obtained after stage 2 & after stages 1 & 3 that are executed in parallel
- What discount factor do we use?

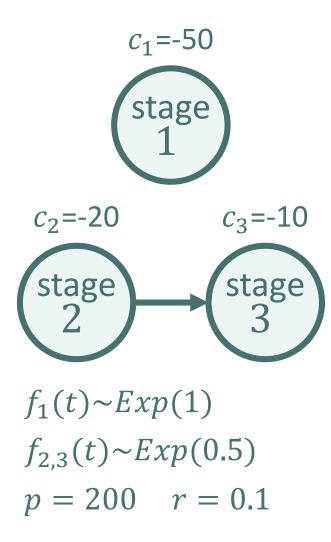
 $- \phi_{2}(r) \phi_{1}(r) \\ - \phi_{2}(r) \phi_{3}(r)$



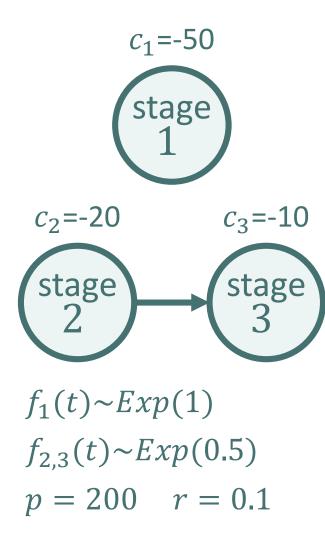
 $f_{2.3}(t) \sim Exp(0.5)$

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 - $\phi_{2}(r) \phi_{1}(r)$ $- \phi_{2}(r) \phi_{3}(r)$
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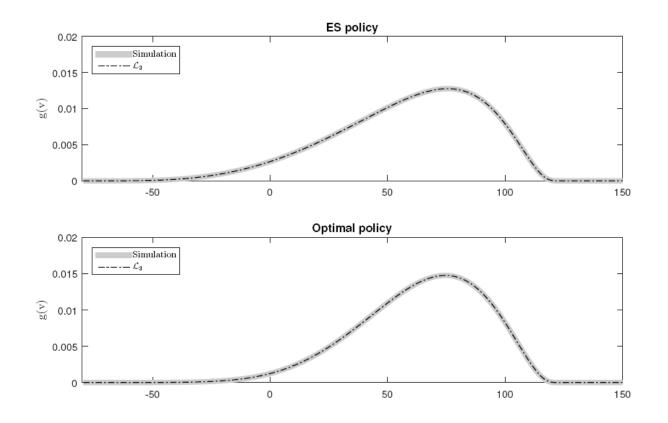
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 - $\phi_{2}(r) \phi_{1}(r) \\ \phi_{2}(r) \phi_{3}(r)$
- The payoff is obtained after the maximum duration of stages 1 & 3!
- ⇒ We need to determine the discount factor for this maximum distribution
- ⇒ If this is not possible, approximations are required!

NPV of a general project

The example below illustrates the accuracy of the three-parameter lognormal distribution (\mathcal{L}_3) for the ES and the optimal policy:



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- The optimal sequence of stages can be found efficiently
- The eNPV of a general project can be obtained using exact, closed-form expressions
- Higher moments & the distribution of the NPV of a general project can be approximated

